

charge on each capacitor is then $Q' = CV'$. By charge conservation, $Q' = Q/2$. This implies $V' = V/2$. The total energy of the system is $= 2 \times \frac{1}{2} Q' V' = \frac{1}{4} QV = 2.25 \times 10^{-6} \text{ J}$

Thus in going from (a) to (b), though no charge is lost; the final energy is only half the initial energy. *Where has the remaining energy gone?*

There is a transient period before the system settles to the situation (b). During this period, a transient current flows from the first capacitor to the second. Energy is lost during this time in the form of heat and electromagnetic radiation.

EXAMPLE 2.10

SUMMARY

1. Electrostatic force is a conservative force. Work done by an external force (equal and opposite to the electrostatic force) in bringing a charge q from a point R to a point P is $V_P - V_R$, which is the difference in potential energy of charge q between the final and initial points.
2. Potential at a point is the work done per unit charge (by an external agency) in bringing a charge from infinity to that point. Potential at a point is arbitrary to within an additive constant, since it is the potential difference between two points which is physically significant. If potential at infinity is chosen to be zero; potential at a point with position vector \mathbf{r} due to a point charge Q placed at the origin is given by

$$V(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \frac{Q}{r}$$

3. The electrostatic potential at a point with position vector \mathbf{r} due to a point dipole of dipole moment \mathbf{p} placed at the origin is

$$V(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \frac{\mathbf{p} \cdot \hat{\mathbf{r}}}{r^2}$$

The result is true also for a dipole (with charges $-q$ and q separated by $2a$) for $r \gg a$.

4. For a charge configuration q_1, q_2, \dots, q_n with position vectors $\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n$, the potential at a point P is given by the superposition principle

$$V = \frac{1}{4\pi\epsilon_0} \left(\frac{q_1}{r_{1P}} + \frac{q_2}{r_{2P}} + \dots + \frac{q_n}{r_{nP}} \right)$$

where r_{1P} is the distance between q_1 and P, as and so on.

5. An equipotential surface is a surface over which potential has a constant value. For a point charge, concentric spheres centred at a location of the charge are equipotential surfaces. The electric field \mathbf{E} at a point is perpendicular to the equipotential surface through the point. \mathbf{E} is in the direction of the steepest decrease of potential.