

$$I = KA^2$$

or  $I = K (a_1^2 + a_2^2 + 2a_1a_2 \cos \phi)$  .....(8)

### Condition for Maxima (Constructive Interference)

For,  $I = I_{\max}$  i.e.  $\phi = 0, \pm 2\pi, \pm 4\pi, \dots = \pm n\pi$  .....(9) where  $n = 0, 1, 2, 3, \dots$

Corresponding value of path difference,  $\Delta x = \pm n\lambda = 0, \pm \lambda, \pm 2\lambda, \pm 3\lambda, \dots$  .....(10)

$$I_{\max} = K(a_1 + a_2)^2 \quad \dots(11)$$

### Condition for Minima

For getting minima at point P i.e.  $I = I_{\min}$

So, by eqn. (8),  $\cos \phi' = 1$

$$\phi' = \pm\pi, \pm 3\pi, \pm 5\pi$$

$$\phi' = \pm (2m - 1)\pi \quad \dots(13)$$

where  $m = 1, 2, 3, \dots$